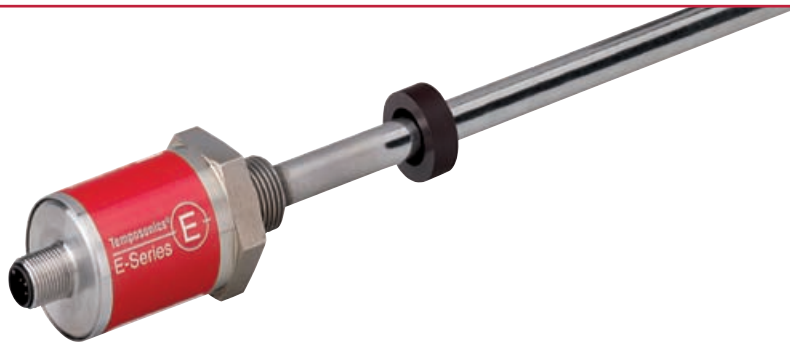


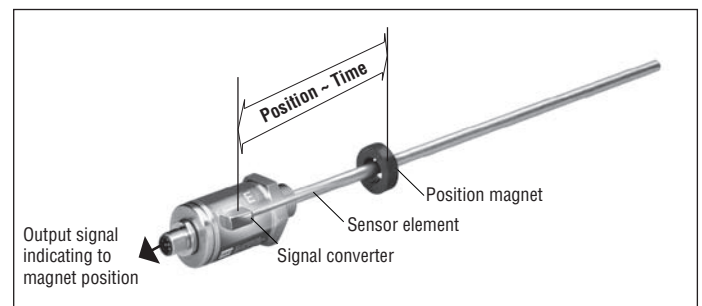
E-Series SSI

Temposonics® EH
Stroke length 50 - 2500 mm

Document Part Number
551297 Revision A



- Linear, absolute measurement
- Contactless sensing with highest durability
- Rugged industrial sensor
- EMC tested and CE marked
- Linearity deviation less than 0.02 % F.S.
- Repeatability 0.005 % F.S.
- Direct signal output for position
- SSI
- Stroke length 50 - 2500 mm



Magnetostriction

The Temposonics® linear position transducers are based on magnetostriction technology. Magnetostriction is a ferromagnetic material phenomenon which relates a dimensional change of the material to its magnetization properties. It is the product of a general coupling between the magnetic and elastic transport properties of the materials crystal lattice. This affect is typically on the scale of a few parts per million. It is quasi linear with the material's magnetization, may be positive or negative, and reaches a maximum at magnetic saturation. It is reversible, but exhibits a hysteric affect if the magnetization does so. Magnetostriction was characterized in the late 19th century, the longitudinal version is called the „Joule“ effect, the torsional version is called the „Wiedemann“ effect, and the reciprocal effect where mechanical stress changes the magnetic properties is referred to as the „Villari“ effect.

Design

Inherently robust, non-contact and wear free, the Temposonics® linear positions transducers provide the best durability and accurate position measurement solutions in harsh industrial environments. The position measurement technique is similar to the radar principle but using magnetostrictive effects. The position measurement accuracy is tightly controlled by the quality of our waveguide which is manufactured by MTS. The sensors are completely modular in electrical and mechanical design. They provide flexibility of use in many different applications. In the EH sensors, a stainless steel pressure rod and mounting flange protects the sensor element from hydraulic cylinder pressures. The sensor head houses the modular electronics which provide the measurement and the choice of various different signal output interfaces. The external position measurement target is a magnet. It is attached to the moving part of the cylinder (the piston) while the transducer itself can be stationary.

Temposonics®-EH

High Pressure Compact Sensor - Stroke length 50 - 2500 mm.

MTS Sensors continues to establish new performance standards for low-cost, fully-industrial, durable position sensors using the widely preferred magnetostrictive technology. This principle for accurate and non-contact measurement of linear-position sensing was developed 30 years ago by MTS and is used with outstanding success in a large variety of industrial applications. The Temposonics® EH sensor provides all the performance you need for your application: the full advantages of magnetostrictive position measurement at optimum costs.

The Temposonics® EH Sensor features a pressure resistant sensor rod for direct stroke measurement inside hydraulic cylinders. With its minimized sensor head and either a 7 mm or 10 mm rod, it is the ideal solution when space is critical. For long strokes, the EH is available with measuring ranges up to 2500 mm. The EH Sensor offers completely sealed stainless-steel housing for long life position measurement in rugged environments. When installed with the appropriate mating connector and cable, it features protection up to IP69K and is suitable for high-pressure washdown applications.

Technical Data

Input

Measuring Variable	Position
Stroke length	50 - 2500 mm

Output

Interface	SSI (Synchronous Serial Interface) - Differential signal in SSI standard				
Data format	Binary or Gray				
Data length	24; 25 bit				
Update time	Up to 3.7 kHz, depending on stroke lengths				
	70 kBaud ... 1 MBaud, depending on cable length				
Data speed	Cable length	<3	<50	<100	<200
	Baud rate	1.0 MBd	<400 kBd	<300 kBd	<200 kBd

Accuracy

Resolution	20 µm, 50 µm or 100 µm
Linearity, deviation	< ± 0.02 % F.S. (Minimum ± 60 µm)
Repeatability	< ± 0.005 % F.S. (Minimum ± 20 µm)
Temperature coefficient	≤ 15 ppm/°C

Operating conditions

Mounting position	Any
Magnet speed	Any
Operating temperature	-40° C ... +75° C
Dew point, humidity	90 % rel. humidity, no condensation
Ingress protection	IP69K if appropriate mating cable connector is correctly fitted
Shock test*	100 g (single shock) IEC-Standard 60068-2-27
Vibration test*	15 g / 10 - 2000 Hz IEC-Standard 60068-2-6 (resonance frequency excluded)
EMC-Test	Electromagnetic emission EN 61000-6-3
	Electromagnetic immunity EN 61000-6-2
	The sensor meets the requirements of the EC directives and is marked with CE

Design / Material

Sensor housing	Stainless Steel 1.4301 / AISI 304
Rod	Stainless Steel 1.4301 / AISI 304
Pressure Rating	7 mm Rod: 300 bar, 350 bar peak
	10 mm Rod: 350 bar, 450 bar peak
Position encoder	Ring magnet, PA-Ferrite

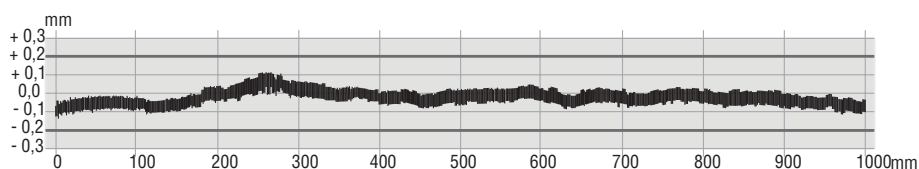
Installation

Mounting type	Threaded flange M18 x 1,5 or 3/4" - UNF
Mounting position	Any

Electrical Connection

Connection type	8 pin M12
Input voltage	24 VDC (+20 % / -15 %)
Current consumption	typically 90 mA
Ripple	≤ 0.288 Vpp
Dielectric strength	500 VDC (DC ground to machine ground)
Polarity protection	≥ -30 VDC
Overvoltage protection	≤ 36 VDC

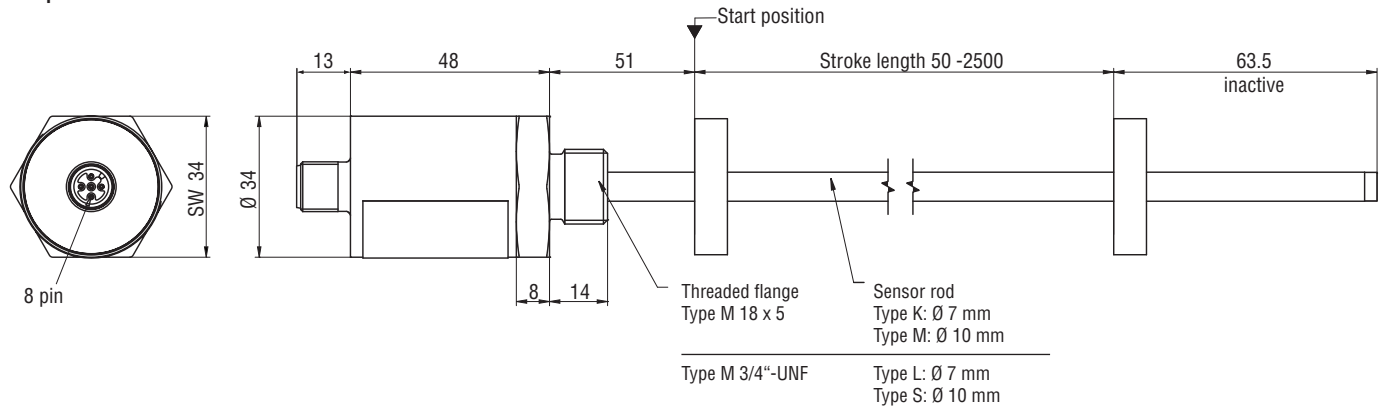
*for 10 mm rod only



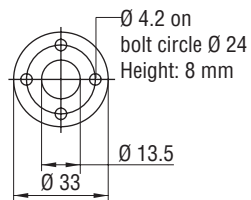
Linearity protocol example

Sensor Temposonics®-EH, Stroke length 1000 mm
Tolerance allowed: ± 0.2 mm
Tolerance measured: typical ± 0.09 mm

Temposonics® EH

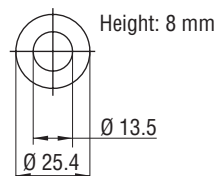


Position magnets (not included in delivery, please order separately)



Ring magnet OD33
Part No. 201 542-2

Composite PA-Ferrite-GF20
Weight: ca. 14 g
Operating temperature: -40 ... +100°C
Surface pressure max. 40N/mm²
Fastening torque for M4 screws
max. 1 Nm



Ring magnet OD25,4
Part No. 400 533

Composite PA-Ferrite
Weight: ca. 10 g
Operating temperature: -40 ... +100°C
Surface pressure max. 40N/mm²

Other magnets on request.

Mounting

The EH sensor is designed for direct stroke measurement inside prepared hydraulic cylinders. At the head of the sensor, a threaded flange and O-Ring provides for mounting and sealing the sensor into a port opening in the cylinder end cap. The sensor's pressure resistant rod fits into a bore drilled through the center of the piston head and rod assembly. The sensor's position magnet is mounted on the top of the piston head or installed in a shallow counter-bore inside the piston head.

The position magnet requires minimum distances away from ferrous metals to allow proper sensor output. The minimum distance from the front of the magnet to the cylinder end cap is 15 mm. The minimum distance from the back of the magnet to the piston head is 5 mm. The nonferrous spacer (part no. 400633), provides this minimum distance when used along with the standard ring magnet (part no. 201542-2).

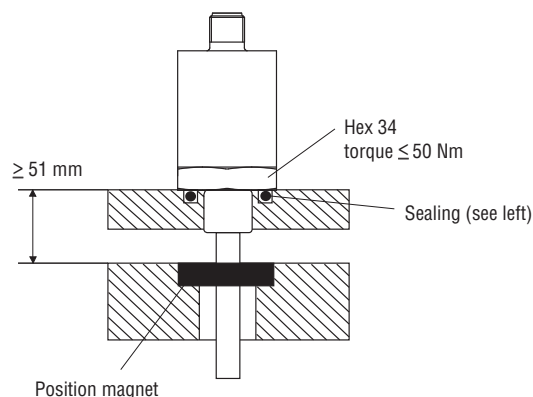
The magnet is usually secured using non-ferrous fastening material (customer supplied). Screws must be made of nonmagnetic stainless steel or brass. In the event that a ferrous circlip or retaining ring will be used to secure the magnet in a counter-bore then an additional non-ferrous spacer (> or = 5 mm) must be placed between the circlip or retaining ring and the front side of the magnet. The cylinder's design ratings for hydraulic pressure and piston velocity will determine the appropriate size for the bore that is drilled through the center of the piston head and rod assembly. The recommended minimum size for this bore is 10 mm when using the 7 mm diameter sensor rod.

Likewise, the recommended minimum size of 13 mm should be used when installing the 10 mm diameter sensor rod. Some applications using long sensor rods may benefit by adding a bushing (e.g. made of flourelastomer material) to prevent wear on the magnet and sensor rod (customer supplied).

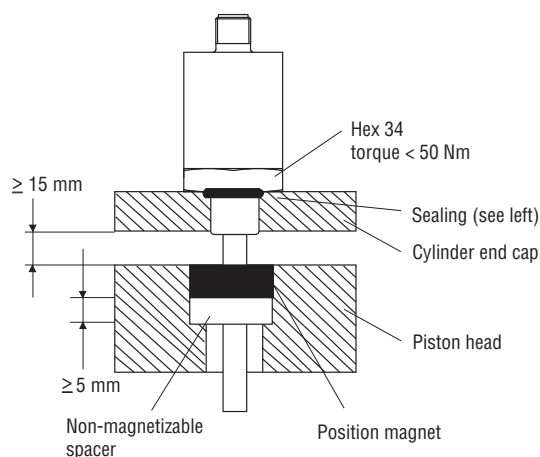
Caution!

For threading the sensor please use only the hexnut at the bottom of the sensor head. Maximum tightening torque is 50 Nm.

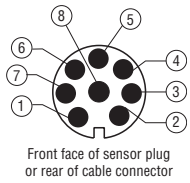
1. Non-magnetizable material



2. Magnetizable material



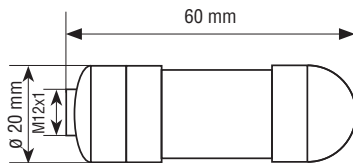
Connector wiring



Connector D84	Function
Pin 1	Clock (+)
Pin 2	Clock (-)
Pin 3	Data (+)
Pin 4	Data (-)
Pin 5	n.c.
Pin 6	n.c.
Pin 7	+24VDC
Pin 8	0V (GND)

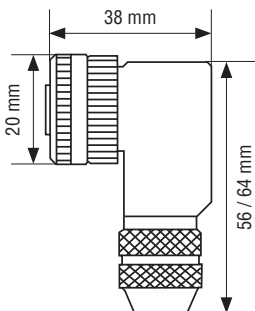
Connectors (not included in delivery, please order separately)

8 pin Female Connector M12 x 1*



Housing: GD-ZnAL / IP67
Termination: screw terminals
Contact insert: CuZn
Max. cable: Ø 4...9 mm
Part No.: 370 694

8 pin 90° Female Connector M12 x 1*



Housing: GD-ZnAL / IP67
Termination: screw terminals
Contact insert: CuZn
Max. cable: Ø 6...8 mm
Part No.: 370 699

* Maximum recommended torque: 0.6 Nm

Temposonics®



Specification

K = Flange M18 x 1,5 / Rod-Ø 7 mm
M = Flange M18 x 1,5 / Rod-Ø 10 mm
L = Flange 3/4"-UNF / Rod-Ø 7 mm
S = Flange 3/4"-UNF / Rod-Ø 10 mm

Stroke length

0050 - 2500 mm

Connection type

D84 - 8 pin cable connector M12

Output

S [1] [2] [3] [4] [5] [6] = Synchronous Serial Interface

[1] Data length: **1** - 25 Bit • **2** - 24 Bit

[2] Output format: **B** - Binary • **G** - Gray

[3] Resolution (mm): **3** - 0,05 • **4** - 0,1 • **5** - 0,02

[4] Performance: **1** - Standard

[5] [6] Options: **00** - Measuring direction forward

Delivery includes:

- Sensor, mounting clamps

Please order separately: accessories (see below)

Stroke length Standard:

Stroke	Ordering steps
≤ 500 mm	5 mm
> 500 - ≤ 750 mm	10 mm
> 750 - ≤ 1000 mm	25 mm
> 1000 - ≤ 2500 mm	50 mm

Accessories

Description	Part No.
Ring magnet OD33	201 542-2
Ring magnet OD25,4	400 533
8 pin female connector M12	370 694
8 pin 90° female connector M12	370 699
8 pin M12 cordset, 5 m PUR shielded cable	370 674
8 pin 90° M12 cordset, 5 m PUR shielded cable	370 676

Notes

[illegible]

www.mtssensor.com
www.temposonics-shop.de
Temposonics® Hotline: +49 2351-9587-6000

Mo-Fr 8 am-19 pm / Sa 8 am-12 pm

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